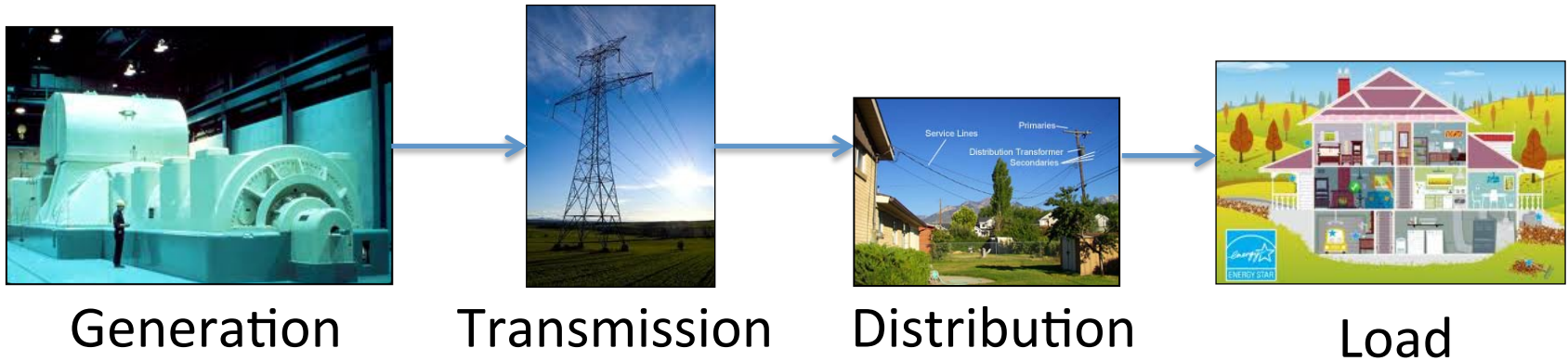


# Frequency Stability Analysis for Inverters in Low Voltage Distribution Systems

Chung-Ching Chang  
EE292K Final Presentation  
June 12, 2012

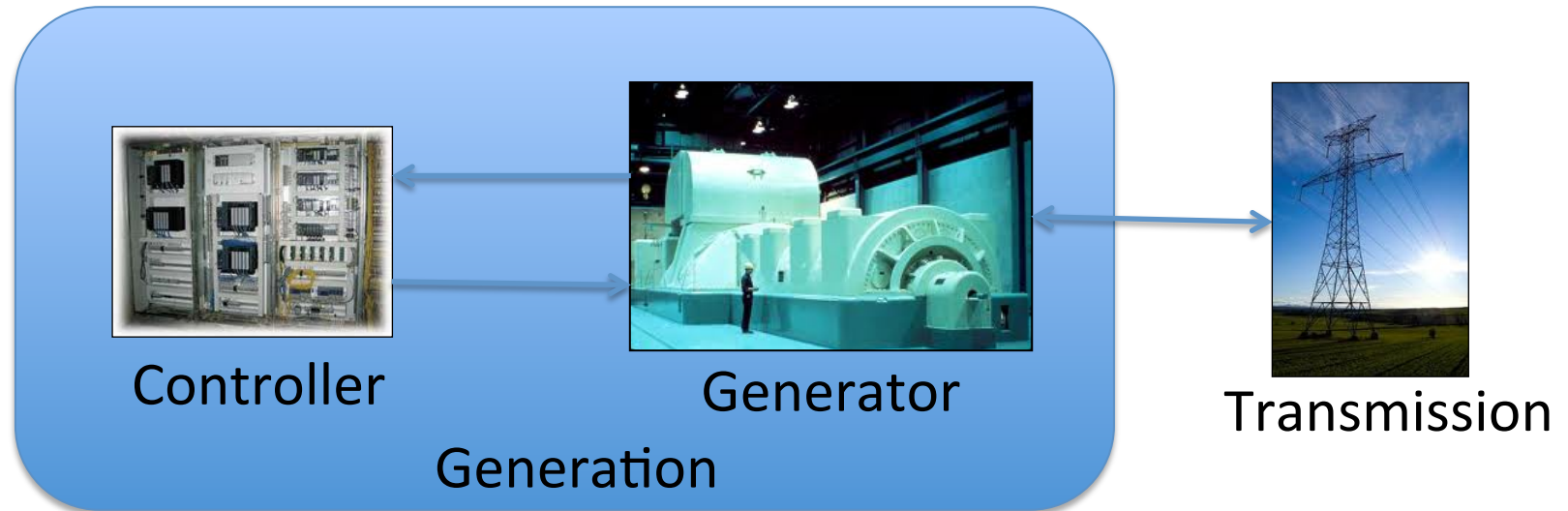
- \* Under the instruction of Prof. Dimitry Gorinevsky and Prof. Sanjay Lall
- \*\* Based on the previous work by Eric Glover

# Traditional Power Grid



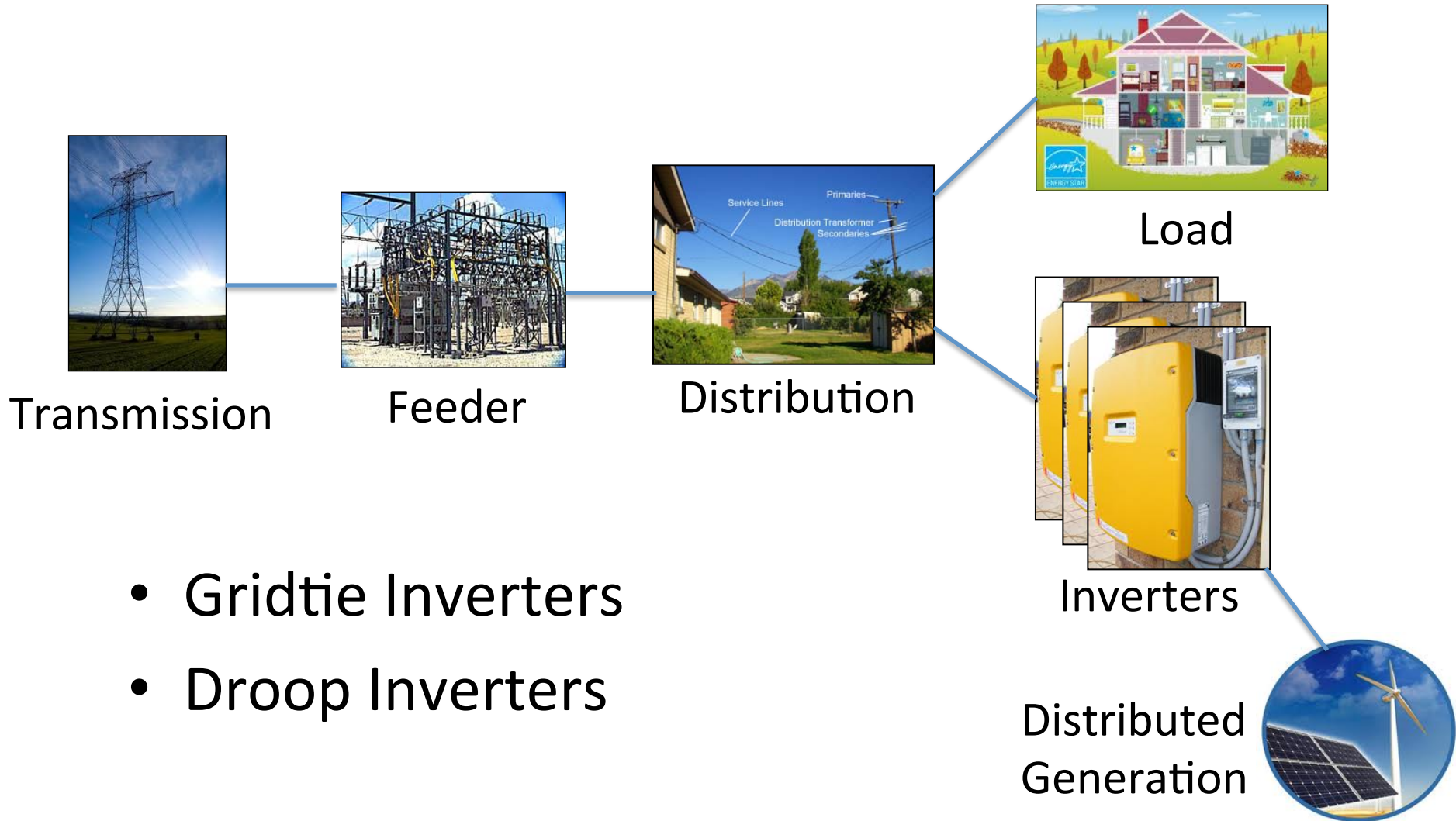
- Unidirectional
- Transform LV/HV for transmission

# Frequency Control in Generation



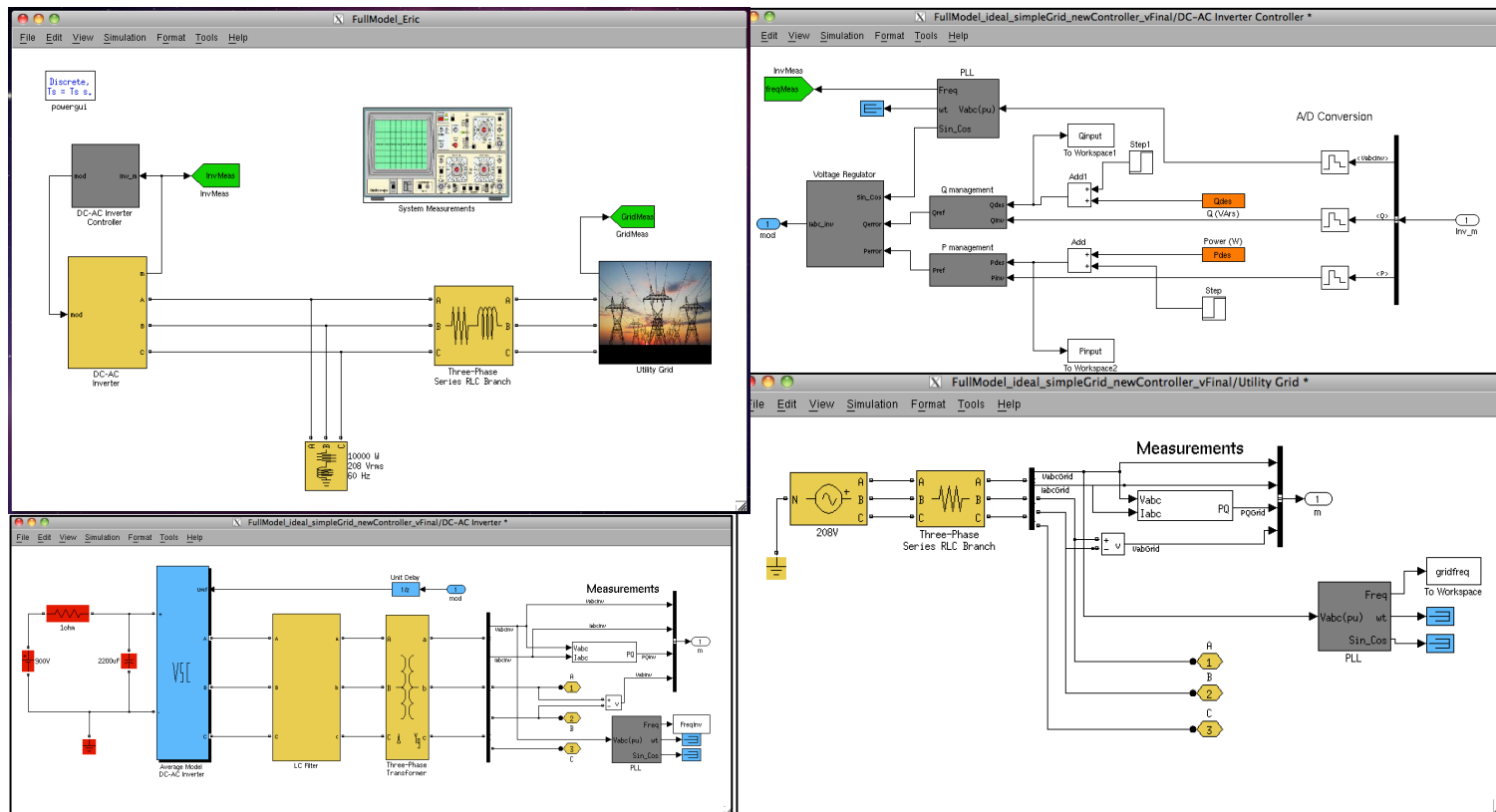
- Primary control
  - Regulates frequency vs. output power
- Secondary control
  - Restores frequency by adjusting turbine valves

# Distributed Generation



# Detailed Simulation

- SimPowerSystems: 3-phase Utility Grid, Inverter, Controls



# Detailed Stability Analysis

- Run detailed simulation to ensure the system is stable
  - With all reasonable combinations of 20 parameters
  - 5 samples for each parameter
  - Each simulation takes 3 minutes
- Total simulation time is 0.5 Billion Years
  - $5^{20} \cdot 180s = 1.72 \cdot 10^{16}s = 544 \text{ Million Years}$

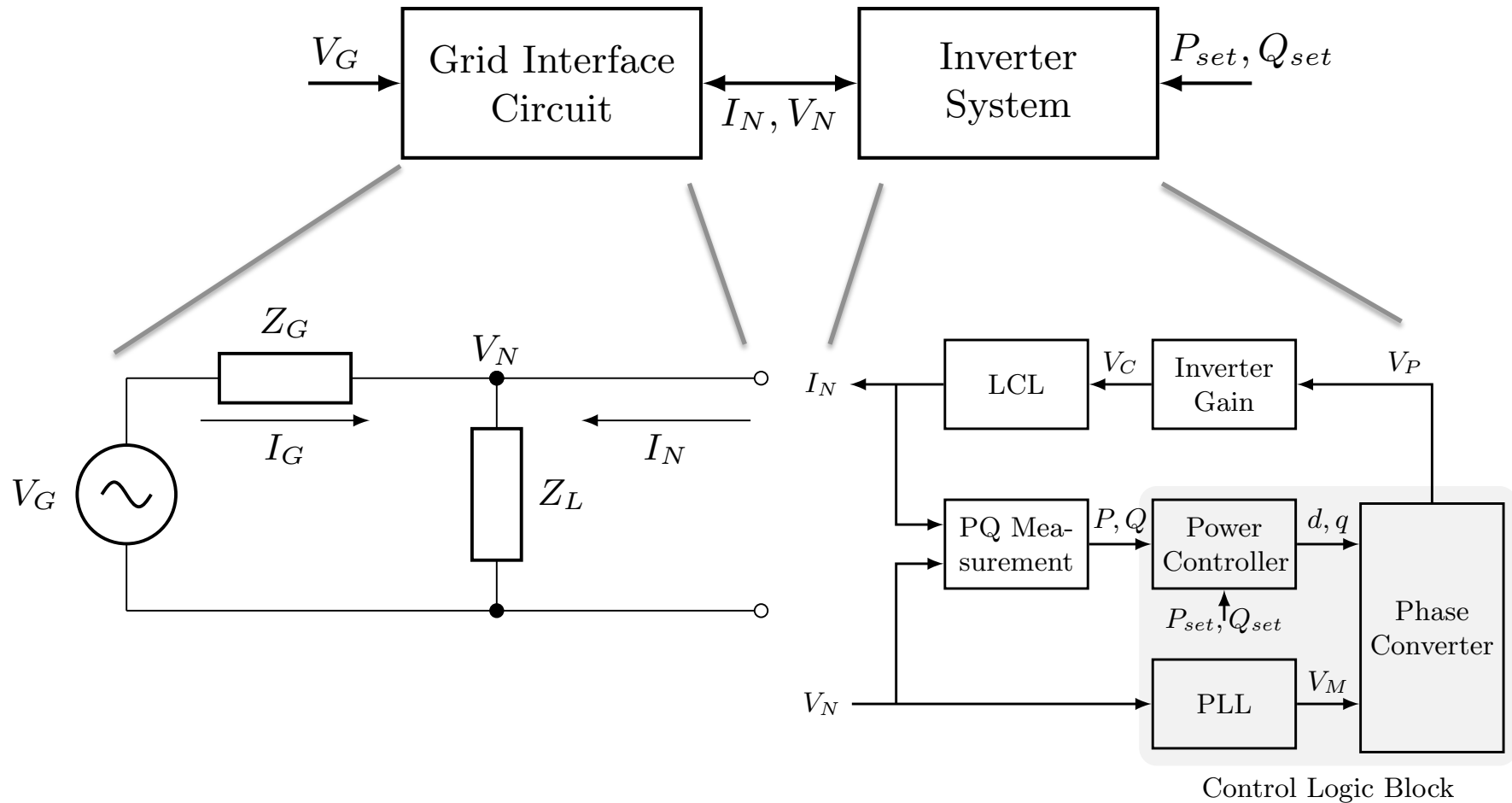
# Surrogate Model

- Single phase system
- System linearized around the steady-state
- Lower computational complexity

	Detailed model	Surrogate model
Number of samples	$5^{20}$	$5^8$
Simulation time	~ 3 minutes	~ 1 second
Total time	$1.72 \cdot 10^{16}$ second	$3.9 \cdot 10^5$ second
Speed-up		~ $\times 10^{11}$

\* More speed-up with sparser parameter samples

# Surrogate Model



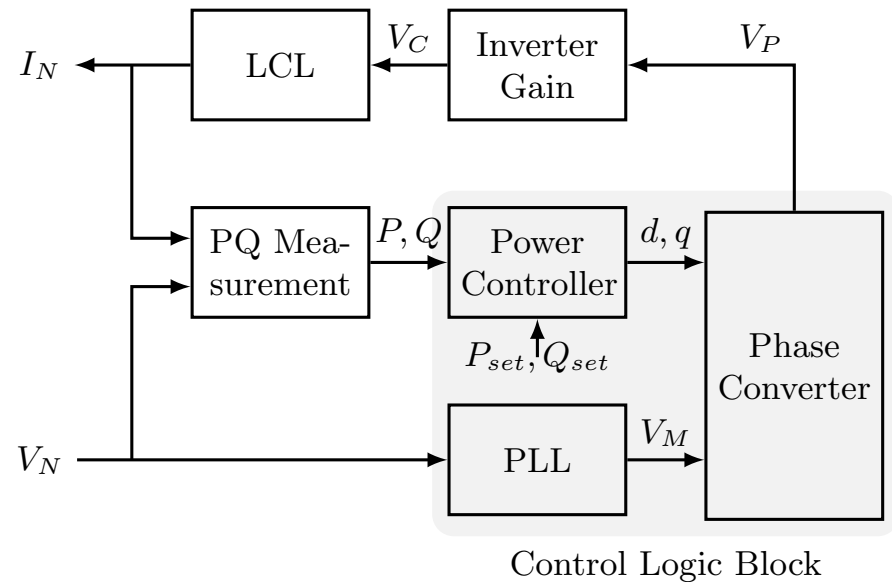


# Gridtie Inverters

- Inject power into the grid with unity power factor:

$$P = P_{\text{set}},$$

$$Q = Q_{\text{set}} = 0$$

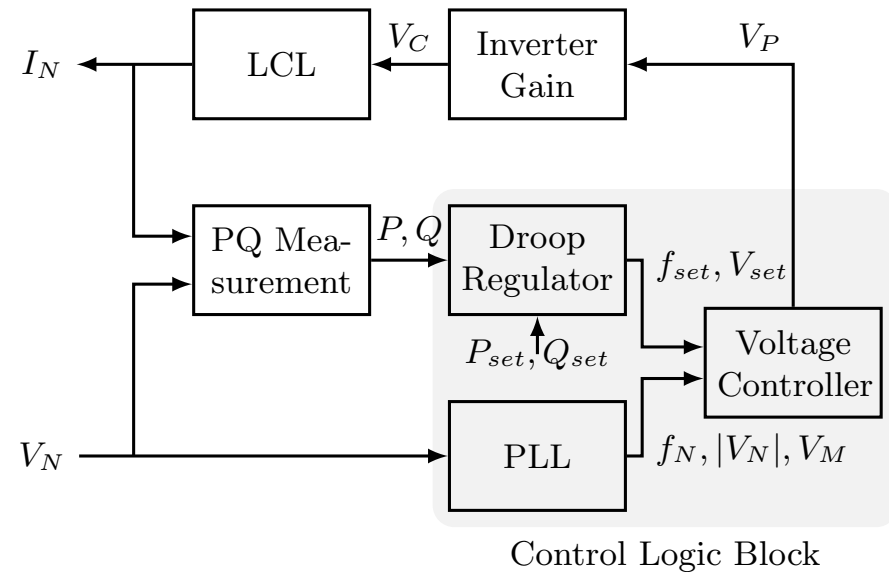


# Droop Inverters

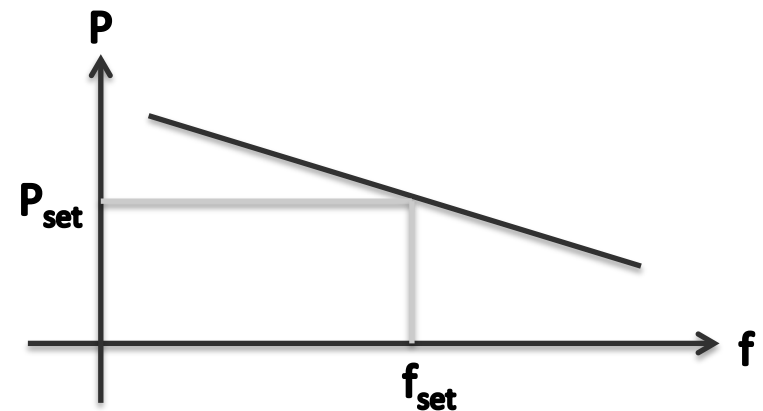
- Droop equations:

$$f_{\text{set}} = f_0 - K_p (P - P_{\text{set}}),$$

$$V_{\text{set}} = V_0 - K_v (Q - Q_{\text{set}})$$

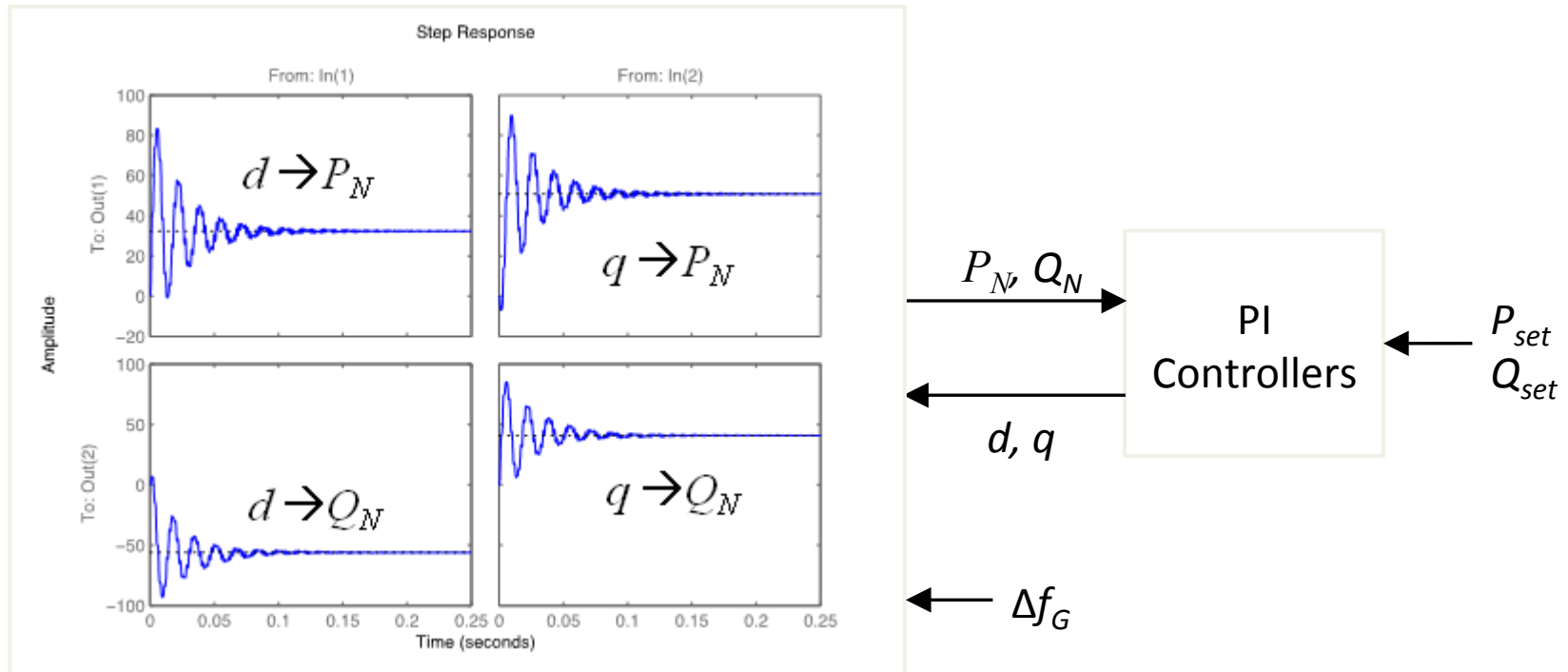


- This adds the inertia to the inverters as that of the primary control in generators



# Control Framework

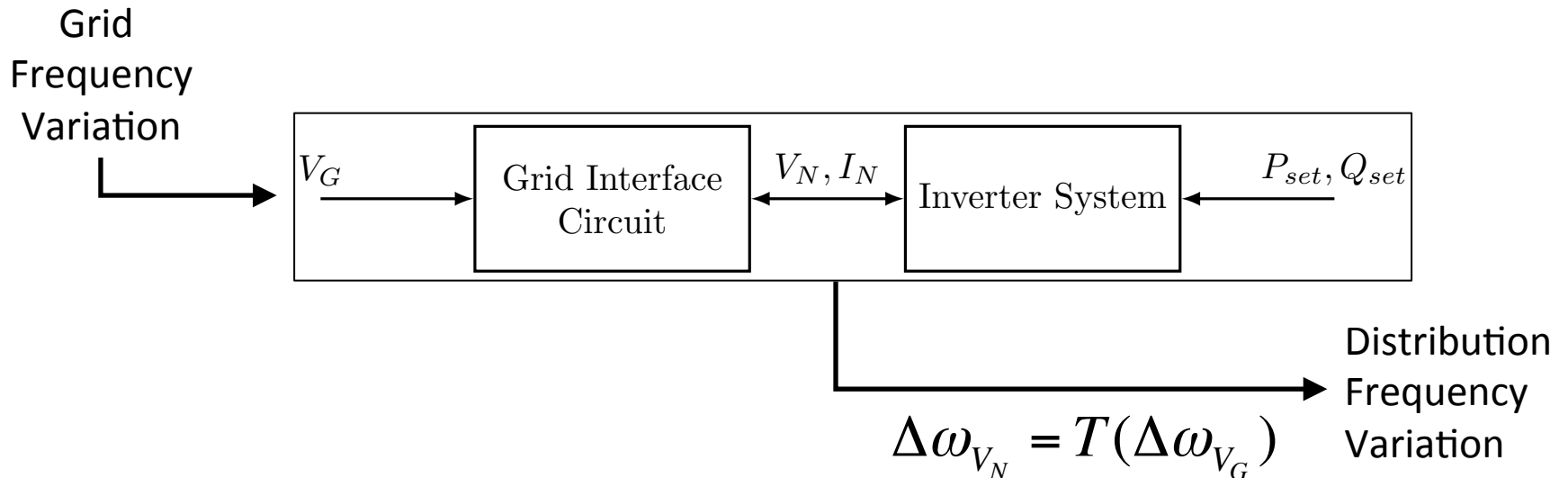
- Stability issues in transient:
  - Set points  $P_{set}$ ,  $Q_{set}$
  - Exogenous frequency disturbance  $\Delta f_G$



# Stability Analysis

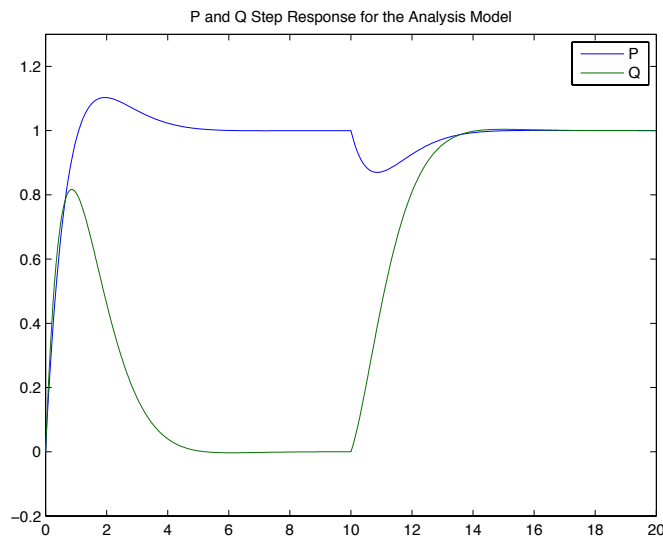
- $H_\infty$  norm measures the worst case disturbance amplification from the frequency of  $V_G$  to that of  $V_N$

$$\|T\|_\infty = \sup \frac{\|\Delta\omega_{V_G}\|_\infty}{\|\Delta\omega_{V_N}\|_\infty}$$

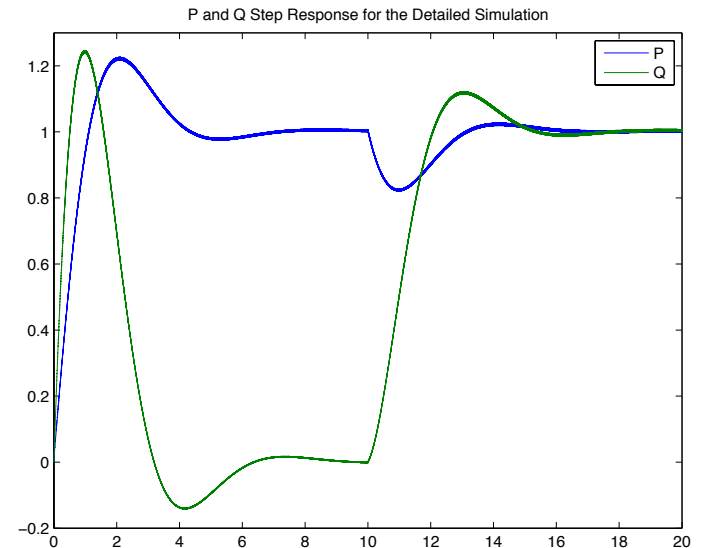


# Surrogate Model Verification

- Surrogate model matches the detailed simulation model reasonably well



Surrogate model



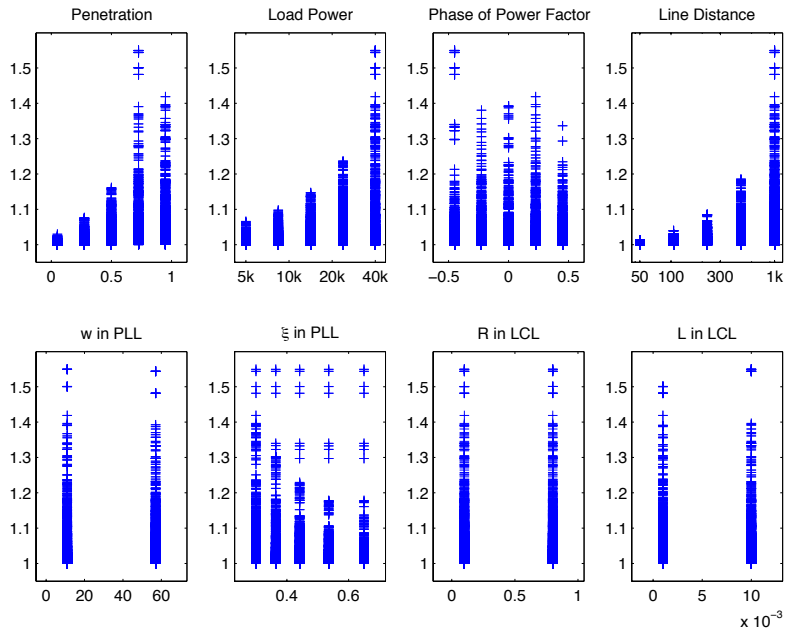
Simulation model

# Analysis Results

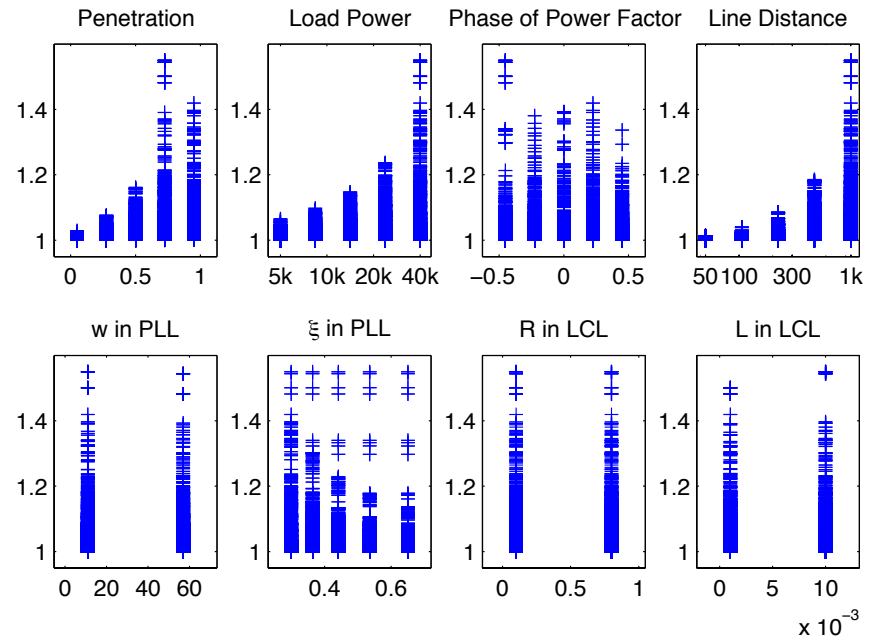
- Range of parameters

Parameters	Minimum Value	Maximum Value
Penetration $a$	0.05	0.95
Load power $P_L$	5kW	40kW
Power factor $\cos(\psi)$	0.9	1.00
Line length $l$	0.25km	1km
PLL rise time	0.02s	0.1s
PLL overshoot	23%	45%
LCL power loss	$1 \cdot 10^{-2}$ Watt	5Watt
LCL settling time	0.12s	0.22s

# Analysis Results



Gridtie Inverter



Droop Inverter

$H_\infty$  norm is always less than 2 in all samples explored!

# Conclusion

- Frequency stability analysis is evaluated for both gridtie and droop inverters
- Grid frequency disturbance is amplified roughly in proportion to penetration, load power, and line distance
- For a well-tuned inverter, this amplification is reasonably small
- However, the power factor may drop below 0.85 as viewed from the upstream as penetration increases, violating IEEE 1547